

## FAST TRACK COMMUNICATION

# The structure of a set of vector fields on Poisson manifolds

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Online at [stacks.iop.org/JPhysA/42/142001](http://stacks.iop.org/JPhysA/42/142001)**Abstract**

We show that the Lie bracket of an arbitrary vector field with a Hamiltonian vector field is the sum of a Hamiltonian vector field and an energy-preserving vector field, but that not all vector fields can be so decomposed.

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We present an algebraic property of a set of vector fields on a symplectic or Poisson manifold that, while simple, does not appear in the standard sources (e.g. [1, 2]). Its novel feature is that it relates *non*-Hamiltonian and Hamiltonian vector fields. It was discovered in the course of an investigation of series of elementary differentials of a vector field used in geometric numerical integration [3].

Let  $(P, \{, \})$  be an  $n$ -dimensional Poisson manifold and  $H: P \rightarrow \mathbb{R}$  a real ( $C^\infty$ ) function on  $P$  that we call the energy. Let  $\mathfrak{X}$  be the Lie algebra of ( $C^\infty$ ) vector fields on  $P$ . The two structures  $\{, \}$  and  $H$  endow  $\mathfrak{X}$  with a distinguished element, namely the Hamiltonian vector field  $X_H$ , and with two Lie subalgebras:  $\mathfrak{X}_{\text{Ham}}$ , the Lie algebra of Hamiltonian vector fields on  $P$ , and  $\mathfrak{X}_H$ , the Lie algebra of energy- (i.e.  $H$ -) preserving vector fields on  $P$ . The Hamiltonian vector field  $X_H$  lies in both  $\mathfrak{X}_{\text{Ham}}$  and  $\mathfrak{X}_H$ .

Elements of  $\mathfrak{X}_H$  are described locally by  $n - 1$  scalar functions, while elements of  $\mathfrak{X}_{\text{Ham}}$  are described by single scalar functions. Thus, it makes sense to ask if an arbitrary vector field  $X$  (described by  $n$  scalar functions) is the sum of a Hamiltonian vector field and an energy-preserving vector field. We shall see that this is (i) true locally near regular points of  $X_H$ , (ii) not necessarily true near singular points of  $X_H$  and (iii) true globally when  $X = [Z, X_H]$  is the Lie bracket of an arbitrary vector field  $Z$  with  $X_H$ . This provides a universal constraint on the range of  $\text{ad}_{X_H}$ . We also have an algebraic description as follows.

**Proposition 1.**  $[\mathfrak{X}, X_H] \subset \mathfrak{X}_{\text{Ham}} + \mathfrak{X}_H$ .

**Proof.** Let  $Z \in \mathfrak{X}$ . We will show that the Hamiltonian part of  $[Z, X_H]$  can be taken to be  $X_{Z(H)}$ . This will be true if the remainder  $[Z, X_H] - X_{Z(H)}$  is energy-preserving, which can be checked as follows:

$$\begin{aligned} ([Z, X_H] - X_{Z(H)})(H) &= Z(X_H(H)) - X_H(Z(H)) - X_{Z(H)}(H) \\ &= 0 - X_H(Z(H)) - \{Z(H), H\} \\ &= -\{H, Z(H)\} - \{Z(H), H\} \\ &= 0. \end{aligned}$$

□

The decomposition is of course only unique up to elements of  $\mathfrak{X}_{\text{Ham}} \cap \mathfrak{X}_H$ , the Hamiltonian vector fields that conserve  $H$ .

**Proposition 2.** *Let  $H \in C^\infty(P)$  and  $Z$  be an arbitrary vector field on  $P$ . (i) In the neighborhood of a regular point of  $X_H$ , there is a Hamiltonian function  $K$  and an energy-preserving vector field  $Y$  such that  $Z = X_K + Y$ . (ii) In the neighborhood of a singular point of  $X_H$ , such  $K$  and  $Y$  need not exist.*

**Proof.** For (i), we have to solve  $Z = X_K + Y, Y(H) = 0$  for  $K$  and  $Y$ . This requires  $Z(H) = X_K(H) + Y(H) = X_K(H) = -X_H(K)$ , that is, the derivative of  $K$  along  $X_H$  is prescribed. In the neighborhood of any regular (i.e. nonzero) point of  $X_H$ , there is a local cross-section transverse to  $X_H$ . Take  $K$  arbitrary on this cross-section and let  $Z(H) = -X_H(K)$  determine  $K$  uniquely away from the cross-section. Then  $Y(H) = Z(H) - X_K(H) = 0$ , that is,  $Y$  is energy-preserving. For (ii), take  $P = T^*\mathbb{R}$  with coordinates  $(q, p)$  and the canonical Poisson bracket, and let  $H = \frac{1}{2}(q^2 + p^2)$  so that the orbits of  $X_H$  are circles centered on the origin. The origin is a singular point of  $X_H$ , and  $X_H(K) = -Z(H)$  has a solution near  $(0, 0)$  for  $K$  only if the integral around each circle centered on the origin of  $Z(H)$  is zero, but there exist  $Z$  (for example,  $Z = q \frac{\partial}{\partial q} + p \frac{\partial}{\partial p}, Z(H) = q^2 + p^2$ ) for which these integrals are nonzero. □

If  $P$  is symplectic, the restriction to regular points of  $X_H$  is equivalent to a restriction to regular points of  $H$ . But if  $P$  is not symplectic, one can take, for example,  $H$  to be a Casimir of the Poisson bracket. Then  $X_K$  and  $Y$  are both energy-preserving, so only energy-preserving vector fields can be decomposed as a sum  $X_K + Y$ .

One can also ask if the decomposition results in propositions 1 and 2 extend to subalgebras of  $\mathfrak{X}$ . For the decomposition to make sense,  $X_H$  must be an element of the subalgebra. We study this for four cases: (1) vector fields with a symmetry, (2) volume-preserving vector fields, (3) elementary differentials of a vector field and (4) vector fields with a first integral.

*Case 1.* If a (discrete or continuous) symmetry acts on  $P$  and the Poisson bracket, and if  $Z$  and  $H$  share the symmetry, then  $X_H$  also has the symmetry, and hence so do  $Z(H), X_{Z(H)}$  and the remainder (the energy-preserving part of the decomposition)  $[Z, X_H] - X_{Z(H)}$ . Thus, proposition 1 holds for symmetric vector fields. Proposition 2(i) does not hold in the symmetric case, by the following counterexample. Let  $P = T^*\mathbb{R}$  as in proposition 2, let  $H = p, X_H = \frac{\partial}{\partial q}$ , and let the symmetry be translation in the  $q$  direction. The invariant Hamiltonians are functions of  $p$  only and their vector fields have  $\dot{p} = 0$ , i.e. they are energy-preserving. But not all invariant vector fields are energy-preserving. Tracing through the proof of proposition 2(i) in this case shows the problem: if  $Z = a(p) \frac{\partial}{\partial q} + b(p) \frac{\partial}{\partial p}$ , the differential equation for  $K, \frac{\partial K}{\partial q} = -b(p)$ , is invariant, but its solution  $K = -qb(p) + c(p)$  is not invariant (and nor is its Hamiltonian vector field  $X_K = (-qb'(p) + c'(p)) \frac{\partial}{\partial q} + b(p) \frac{\partial}{\partial p}$ ). An invariant

differential equation need not have any invariant solutions. Proposition 2(ii) holds in the symmetric case, but is vacuous (take the trivial group).

*Case 2.* If  $Z$  and all Hamiltonian vector fields are volume-preserving, then so are  $[Z, X_H]$  and  $X_{Z(H)}$ ; so proposition 1 holds. Propositions 2(i) and (ii) hold too, because the volume-preserving nature of  $Z$  does not enter the argument.

*Case 3.* On  $P = \mathbb{R}^n$  with a constant Poisson structure,  $X_H =: f$ , the linear combinations of  $f$  and its derivatives (the *elementary differentials* of  $f$ ) span a Lie algebra  $\mathfrak{B} := \text{span}(f, f'(f), f''(f, f), f'(f'(f)), \dots)$ . It is typically countably infinite dimensional. Some of its elements are energy-preserving (e.g.  $f'(f'(f))$ ) and some are Hamiltonian (e.g.  $f''(f, f) - 2f'(f'(f))$ ). If  $Z \in \mathfrak{B}$  then  $[Z, X_H] \in \mathfrak{B}$  and  $X_{Z(H)} \in \mathfrak{B}$ , so the decomposition holds in elementary differentials, too. Proposition 2(ii) holds too; the Hamiltonian and energy-preserving elementary differentials, and those not in their span, can be enumerated [3]. Proposition 2(i) does not hold in this case, because a local decomposition would determine the elementary differentials in a global decomposition.

*Case 4.* For vector fields with a given first integral, the decomposition result does not hold even locally. Consider  $P = T^*\mathbb{R}^2$  with the canonical bracket and vector fields with first integral  $q_1$ . Then  $\frac{\partial H}{\partial p_1} = 0$  and the  $q_1$ -component of  $Z$  is zero and we seek a decomposition  $Z = X_K + Y$  with  $Y(H) = 0$  and  $\frac{\partial K}{\partial p_1} = 0$ . As in the proof of proposition 2, we need  $X_H(K) = -Z(H) = -Z_{q_2}(q_2, p_1, p_2)\frac{\partial H}{\partial q_2} - Z_{p_2}(q_2, p_1, p_2)\frac{\partial H}{\partial p_2}$ ; clearly,  $K$  cannot be independent of  $p_1$  for all such  $Z$ . Replacing  $Z$  by, say,  $[\tilde{Z}, X_H]$  does not help, so proposition 1 does not hold in this case either.

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